

# modelling printed circuit antennas by boundary method

N. El Alami(\*), B. Kebaili(\*\*), B. Bandelier(\*\*), F. Rioux-Damidau(\*\*),

(\*) ECIME, UCP-ENSEA, 95031 Cergy-Pontoise, France

(\*\*) U2R2M, Université Paris XI, ESA CNRS 8081, Bat 220, 91405 Orsay, France

## 1 Introduction

Printed circuits are made of very thin metallic opened shells put on a dielectric material. It is an essential problem to determine their response when they are immersed into an electromagnetic field.

When the field is at low frequency and when the metallic shell is closed (it entirely covers the dielectric), the problem has been solved by introducing potentials; but those methods do not permit to treat high frequencies and cannot take into account opened shells. We here present a formulation suited to this problem.

## 2 Physical Problem

The system is made of a dielectric plate  $\Omega$  of permittivity ( $\varepsilon = \varepsilon_0 \varepsilon_r$ ) and permeability  $\mu_0$ ; on its surface  $\Gamma$  is a conducting circuit of very small thickness  $d$  and conductivity  $\sigma$ . The outside domain is the air. This system is put into a high frequency electromagnetic source field ( $e^s, h^s$ ) at frequency  $\omega$  and the penetration-depth  $\delta$  is such that:  $\delta \gg d$ ; so, in the circuit, electric field  $e$  and current density  $j = \sigma e$  are constant over  $d$ . Moreover, as  $d$  is greatly smaller than the other dimensions we consider that the metallic circuit  $\Gamma_c$  is geometrically a part of  $\Gamma$ ; the rest of  $\Gamma$  is called  $\Gamma_d$  (dielectric part) and thus  $\Gamma = \Gamma_c \cup \Gamma_d$ . The line between  $\Gamma_c$  and  $\Gamma_d$  is called  $\gamma_0$ .  $n$  is the outside normal to  $\Gamma$  and  $N$  is the outside normal to  $\gamma_0$  on  $\Gamma$ . The example of an annulus circuit is showed in Fig. 1.

We define surface current  $J_c$  by:

$$\begin{aligned} J_c &= \sigma d e & \text{on } \Gamma_c \\ J_c &= 0 & \text{on } \Gamma_d \end{aligned} \quad (1)$$

According to Maxwell's equation, the jumps across  $\Gamma$  of the tangential fields are

$$[n \times h]_{\Gamma} = J_c, \quad [n \times e]_{\Gamma} = 0.$$

## 3 Variational Formulation

In the case of a dielectric material completely covered with a conducting thin shell we have proposed [1] a variational formulation to compute the fields

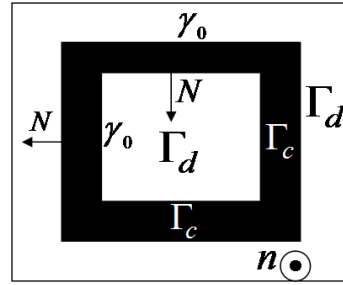


Figure 1: The Annulus circuit

and the current in the shell which uses the integral representation of the electromagnetic fields at high frequencies obtained by Stratton-Chu's formulae [2], [3] but, in the case where the dielectric is partially covered, it cannot be applied because the lineic charges appearing on  $\gamma_0$  need to be taken into account.

Here, we also use Stratton-Chu's formulae.

We call  $e^a, h^a$  the tangential components of the electromagnetic fields by the side of the air and  $G_a$  the Green function in the air:

$$G_a(x, y) = \frac{e^{ik_a|x-y|}}{4\pi|x-y|} \text{ with } k_a^2 = \varepsilon_0 \mu_0 \omega^2.$$

We have  $e^d$  and  $h^d$  by the side of  $\Omega$  with Green fonction  $G_d$  in the dielectric:

$$G_d(x, y) = \frac{e^{ik_d|x-y|}}{4\pi|x-y|} \text{ with } k_d^2 = \varepsilon_0 \varepsilon_r \mu_0 \omega^2.$$

We define the unknown quantities  $e$  and  $h$ :

$$n \times h = n \times h^a = n \times h^d + J_c, \quad (2)$$

$$n \times e = n \times e^a = n \times e^d. \quad (3)$$

These equations are very important because they permit, after using boundary methods, to present a variational formulation implying only  $\Gamma$  by taking as unknown quantities the tangential components of fields  $e$  and  $h$  and the current  $J_c$  on  $\Gamma$ . We use the integral representation of the electromagnetic fields in the air and in the dielectric and write them under a variational form with test functions

on  $\Gamma$ . We obtain:

$$\begin{aligned}
& -i\omega\varepsilon_0 \int_{\Gamma} \int_{\Gamma} (n(x) \times e'(x)) \cdot (n(y) \times e(y)) (G_a + \varepsilon_r G_d) \\
& - \frac{1}{i\omega\mu_0} \int_{\Gamma} \int_{\Gamma} \operatorname{div}_{\Gamma} (n(x) \times e'(x)) \\
& \quad \operatorname{div}_{\Gamma} (n(y) \times e(y)) (G_a + G_d) \\
& + \int_{\Gamma} \int_{\Gamma} (n(x) \times (e'(x) \times (n(y) \times h(y))) \cdot \operatorname{grad}_x (G_a + G_d) \cdot \\
& - \int_{\Gamma} \int_{\Gamma_c} ((n(x) \times e'(x)) \times J_c) \cdot \operatorname{grad}_x G_d \\
& \quad + \frac{1}{2} \int_{\Gamma_c} e' \cdot J_c = - \int_{\Gamma} (n \times e') \cdot h^s, \quad (4)
\end{aligned}$$

and:

$$\begin{aligned}
& i\omega\mu_0 \int_{\Gamma} \int_{\Gamma} (n(x) \times (h'(x)) \cdot (n(y) \times h(y)) (G_a + G_d) \\
& - i\omega\mu_0 \int_{\Gamma} \int_{\Gamma_c} (n(x) \times h'(x)) \cdot J_c(y) G_d \\
& + \frac{1}{i\omega\varepsilon_0} \int_{\Gamma} \int_{\Gamma} \operatorname{div}_{\Gamma} (n(x) \times h'(x)) \\
& \quad \operatorname{div}_{\Gamma} (n(y) \times h(y)) (G_a + \frac{G_d}{\varepsilon_r}) \\
& \quad + \frac{1}{i\omega\varepsilon_0} \int_{\Gamma} \int_{\gamma_0} \operatorname{div}_{\Gamma} (n(x) \times h'(x)) J_c \cdot N \frac{G_d}{\varepsilon_r} \\
& + \int_{\Gamma} \int_{\Gamma} (n(x) \times h'(x)) \times (n(y) \times e(y)) \cdot \operatorname{grad}_x (G_a + G_d) \\
& \quad = - \int_{\Gamma} (n \times h') \cdot e^s. \quad (5)
\end{aligned}$$

We notice that we can not replace  $J_c$  by its value (1) and limit the problem to two unknown quantities because the problem will then be badly defined.

The double integral  $\int_{\Gamma} \int_{\gamma_0}$ , where  $\int_{\gamma_0}$  is a line integral, permits to take into account the lineic charges which appear on  $\gamma_0$ . It comes from  $\operatorname{div}_{\Gamma} J_c$  which is null except on  $\gamma_0$  where it is equal to  $-J_c \cdot N \delta_{\gamma_0}$ . From (1) with  $J'$  as a test function defined only on  $\Gamma_c$ , we write :

$$\int_{\Gamma_c} J_{\Gamma} \cdot J' - \int_{\Gamma_c} \sigma d e \cdot J' = 0, \quad (6)$$

Equation (6) is very important because it permits to have the unicity of the solution of the formulation.

It appears that the formulation, made of (4) (5) and (6), depends only on product  $\sigma d$  and not directly on  $\sigma$  or  $d$ .

For the discretization, surface  $\Gamma$  is meshed into triangles. Fields  $e$  and  $h$ , which appear by their tangential components, are discretized with Nédélec's edge elements and the degrees of freedom are the

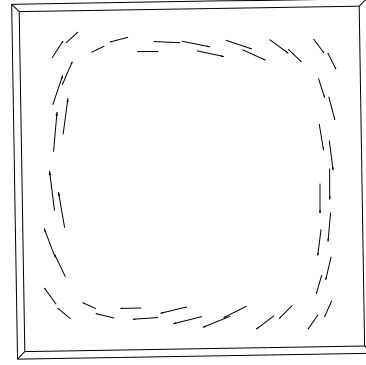


Figure 2: The current density in a conducting annulus with a slit

fields circulations along the edges. Current  $J_c$  is discretized with edge elements rotated by  $\pi/2$  the degrees of freedom being the fluxes through the edges.

## 4 Numerical Results

The presented variational formulation, which only uses the unknown quantities in the air on the surface of the domain, has been applied to many examples. All the obtained results show that surface current is well presented in a printed circuit or generally in an opened shell as soon as the thickness of the metal is very small.

Fig 2 shows surface current  $J_c$  in the case of a dielectric plate ( $L = l = 12 \text{ cm}$ ,  $H = 2 \text{ cm}$ ,  $\varepsilon_r = 25$ ), on which there is a conducting annulus (width =  $1 \text{ cm}$ ,  $\sigma d = 0.01 \text{ S}$ ) with a slit in the middle of the left side; it is put into a plane wave.

This formulation can be used, in particular, to model the antennas used in MRI.

## References

- [1] B. Kebaili, B. Bandelier and F. Rioux-Damidau "Modelling a thin shell submitted to an electromagnetic wave" *IEEE Trans. Magn.*, vol 37, 2001, pp. 3277-3280.
- [2] J. A. Stratton, *Electromagnetic theory*, Mac Graw Hill, New York, 1941.
- [3] V. Levillain, "Couplage éléments finis-équations intégrales pour la résolution des équations de Maxwell en milieu hétérogène," *PHD Thesis*, Polytechnique, Palaiseau, 1991.